

Abstract

A method for externally locating anomalies located inside an immersed hollow structure (PL), wherein said anomalies are previously detected by a device (RTE) moving inside said immersed hollow structure, and are positioned by counting a series of reference marks from an origin, said reference marks being located at regular intervals and being accessible from the inside and outside of said immersed hollow structure. The inventive method consists in defining by means of counting a reference mark, starting from said origin, which is accessible from the outside of the immersed hollow structure; positioning a transponder module (T) on said reference mark; identifying the transponder module (T) by an I.D. code; determining the number of reference marks separating the anomalies and the identified transponder module (T).